Dr. Russ Tedrake is the Vice President of Robotics Research at Toyota Research Institute (TRI). Dr. Tedrake leads the Large Behavior Models division at TRI, which is building foundation models for dexterous robotic manipulation. The team includes world-class researchers who focus on machine learning (especially computer vision and large multimodal models), dynamics and simulation, human-robot interaction, and hardware and software for dexterous manipulation.

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